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k  
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(Dashti *et al.*, 2010)

(Kasiri & Safabakhsh, 2007)

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(Keagy *et*

(1998 & 2000) Shiranita *et al.* ,1996)

(2007) Omid *et al.* .

(2010) Wang *et al.* .(Cheng *et al.*, 2008)

(

(Cetin *et*

(Kulak, 2002; Fan & Xia, 2003)

*al.*, 2004; Pearson, 2001)  
(1997) Ghazanfari *et al.*

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(Latif *et al.*, 2000; Lee & Pun, 2000)

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1. Fourier Descriptors
  2. Neural Network
  3. Decision tree

, ( )

$$g_{m,n}(x, y) = a^{-m} g(x', y') \quad a > 1 \quad ( )$$

$n = 0, 1, 2, \dots, k-1$        $m = 0, 1, 2, \dots, s-1$

$$x' = a^{-m} (x \cos \theta + y \sin \theta)$$

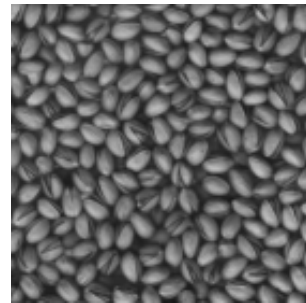
$$y' = a^{-m} (-x \sin \theta + y \cos \theta)$$

$$\theta = \frac{n\pi}{k}$$

(Lambert & Bock, 1997; Latif *et al.*, 2000; .

Lee & Pun, 2000; Fan & Xia, 2003)

$g_{m,n}$   
 $a$   $g(x, y)$   
 $n$   $m$   
 $y'$   $x'$



(Haley & Manjunath ,

(Ahmadian *et al.*

1995; Vo *et al.*, 2006)

(Han & K-

2004; Clausi & Jernigan, 2000)

(Allier & Emptoz, 2003)

Kuang, 2007)

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(Clausi & Jernigan, 2000; . ( )

Smeulders *et al.*, 2000; Ahmadian & Mostafa, 2003;

Ahmadian *et al.*, 2004; Nezamabadi-pour *et al.*, 2003)

( )

$$g(x, y) = \frac{1}{2\pi\sigma_x\sigma_y} \exp\left(-\frac{1}{2}\left(\frac{x^2}{\sigma_x^2} + \frac{y^2}{\sigma_y^2}\right)\right) \times \exp(j2\pi u_0 x) \quad ( )$$

x

$$G(u, v) = \exp\left(-\frac{1}{2}\left(\frac{(u-u_0)^2}{\sigma_u^2} + \frac{v^2}{\sigma_v^2}\right)\right) \quad ( )$$

dpi

HP ScanJet 6300c

$$\begin{matrix}
 u_0 \\
 \sigma_y \quad \sigma_x \quad x
 \end{matrix}$$

( )

( )

y x

$$\sigma_v = \frac{1}{2\pi\sigma_y} \quad \sigma_u = \frac{1}{2\pi\sigma_x}$$

k

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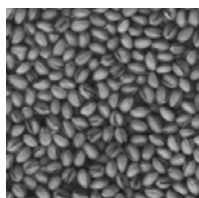
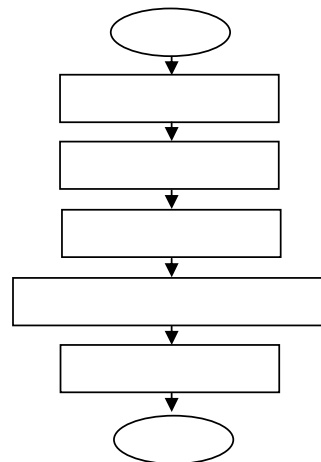
$g(x, y)$

3. Rotation
4. Orientation
5. Scale
6. k Nearest Neighbors

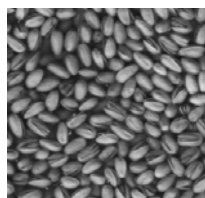
1. Gabor Filters
2. Extension

...

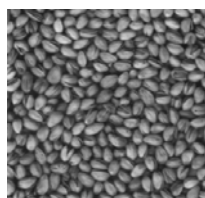
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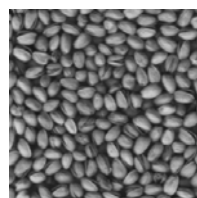
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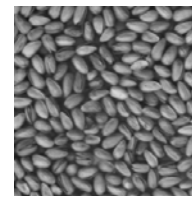
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MPEG-7

(Manjunath et al., 2002)

$$I_{m,n}(x, y) = f^{-1}[I(u, v)G_{m,n}(u, v)] \quad ( )$$

$$G_{m,n}(u, v) = \frac{I_{m,n}(x, y) - \mu_{m,n}}{\sigma_{m,n}} \quad ( )$$

$$\sigma_{m,n} = \sqrt{\iint (I_{m,n}(x, y) - \mu_{m,n})^2 dx dy} \quad ( )$$

$$\mu_{m,n} = \iint |I_{m,n}(x, y)| dx dy \quad ( )$$

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