

() , ()

(MF-285)

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(/ / : / / :)

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(GPS)

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(McBratney et al., 2005)

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(Yule et al., 1999)

ahemmat@cc.jut.ac.ir

1. Precision Farming

*

, ()

.(Murphy, 1993)

(Tompkins & Wilhelm, 1982)

(Khalilian et al., 1989)

(Griffith et al., 1988; Thomson & Shinnars, 1987)

.(Khalilian et al., 1989)

.(Alimardani et al., 1989)

(Alimardani et al., 1989; Clark & Adsit, 1985; Grevis-James & Bloome, 1982; McLaughlin, et al., 1993; Tompkins & Wilhelm, 1982)

(Khalilian et al., 1989; Lotfi et

al., 2007; RNAM, 1983).

(GPS) ^

.(Morgan & Ess, 1997)

.(Raheman & Jha, 1997)

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(ASAE, S296.2,

DEC03)

π

() Grevis-James

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.(Raheman & Jha, 1997)

.(Yahya, 2003; Yule et al., 1999)

-
- 7. Radar speed sensor
 - 8. Ultrasonic speed sensor
 - 9. Global Positioning System (GPS)
 - 10. Encoder shaft
 - 11. Proximity switch

-
- 1.Sensors
 - 2.Data acquisition systems
 - 3.Spatial variability
 - 4. Parameter
 - 5. Draft
 - 6. Tractive efficiency

... :

(Morgan () Yule et al. . & Ess, 1997) () Masoumi & Logavi
() Hemmat & Asadi Khashoei .
(DGPS)

(Alciatore &. Histan, .2003) (Alciatore &. Histan, .2003)
(: (MF-) ()'
() Alimardani et al., .
و (" در

(Lotfi et al., 2007)
()
(Yahya, 2003)

(MF-) Grevis- . () James
(: ()
()
(McLaughlin, .1993; Tompkins & Wilhelm, 1982)
(GPS)

) GPS

4. Differential GPS
5. Proximity sensor

1. Compression ignition (CI)
2. Micro oval
3. Hall effect

()

$$= \times \pi \times / = / \text{ m}$$

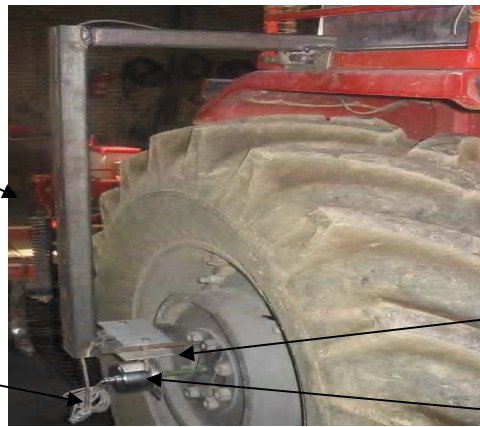
$$\Rightarrow \frac{4.68\text{m/Rev}}{400\text{Pulse/Rev}} = 0.0117\text{m/Pulse}$$

(Lotfi et al., 2007)

1. Flexible coupling
2. Kingpin

پایه نگهدارنده

شفت انکدر



فلنج مستطیلی شکل

اتصال انعطاف پذیر

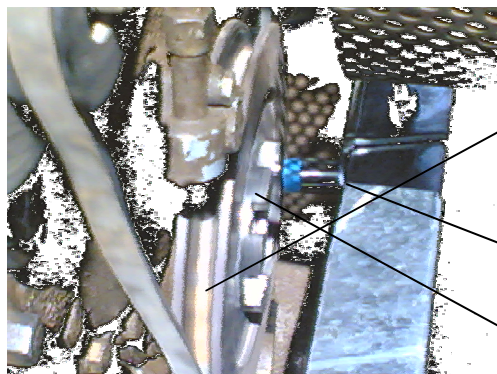
پایه نگهدارنده

شفت انکدر



فلنج مستطیلی شکل

اتصال انعطاف پذیر



حلقه زائده دار

پایه حسگر

حسگر القایی

(Garmin

.Etrex Owner's manual, 2003)

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()

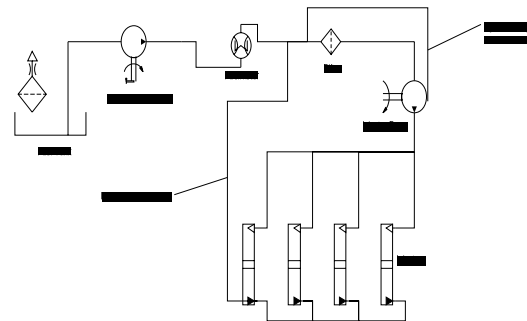
RSMC⁴

RSMC FCMC

FCMC⁵

()

(MF-)



SGMC⁶

GPS .

GPSC⁷



()

TPHD

C⁺⁺

GPS δ

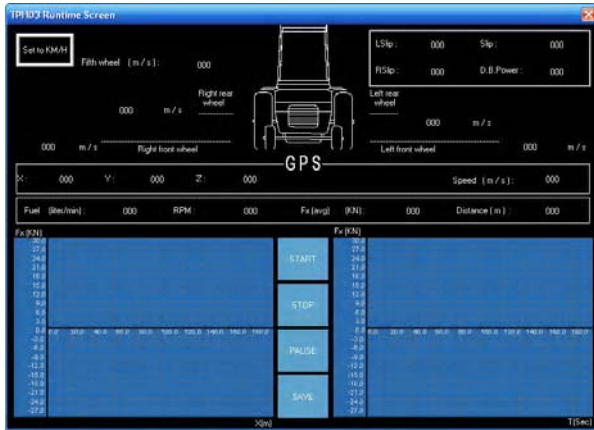
-
- 3. Distributed network
 - 4. Rotary Speed Meter Card
 - 5. Fuel Consumption Meter Card
 - 6. Strain Gauge Meter Card
 - 7. Global Positioning System Card

-
- 1. Roto
 - 2. Garmin

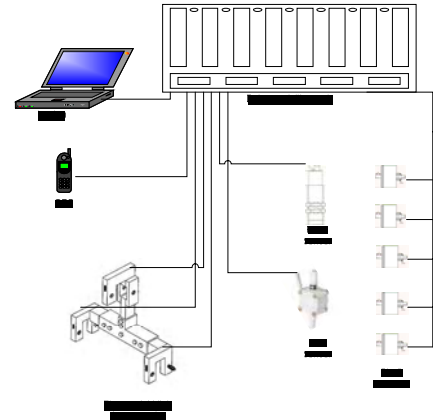
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Com1



TPHD



TPHD

δ Test RUN

Runtime

$$\delta = \frac{\text{Slip}}{\text{Speed}} \times 100 \quad (1)$$

$$\text{Power (kW)} = \text{Force (kN)} \times \text{Velocity (m/s)} \quad (2)$$

TPHD

Runtime ()

3. Reflector
4. Pulley

1. Slip
2. Drawbar power

(U650)

()

(Hemmat et al., 2000; RNAM,

در "

1983)

(:

(Lotfi et al., 2007)

((MF-)

) (U-650)

/ ("

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U-650

TPHD Owen et
Andrade-Sánchez et al., (2003) .al., (1990)

.(Alciatore & Histan, 2003)

(FFT)

×

$$X(f) = \int_{-\infty}^{+\infty} x(t) \cdot e^{-2j\pi ft} dt$$

((d₁₇) (d₁₄)

x(t) X(f)
f t

x(t) j= √ 1

(m₃) / (m₂) / (m₁) /

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MatLab

Khalilian et al. (1989)

Excel

r

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GPS

TPHD

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f

GPS

GPS

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- 2. Standard error
- 3. Stop - watch
- 4. Skid

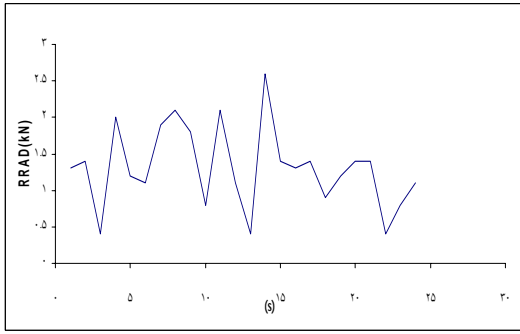
1. Post processing

()

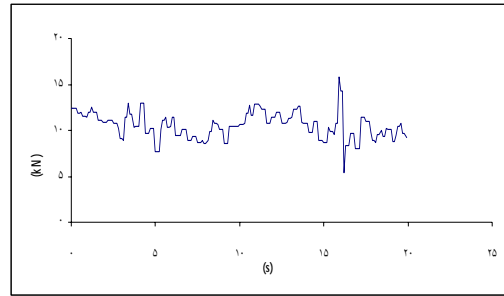
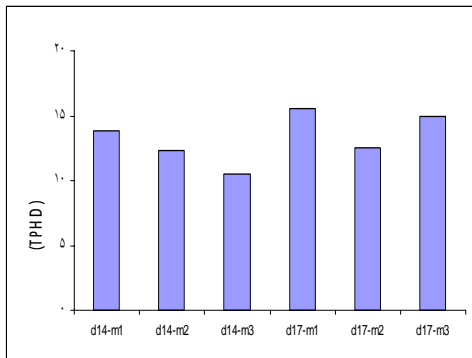
GPS

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RRAD).
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m d.

(DRRAD)
(RRAD)

(Draft_{AD})

()

DRRAD

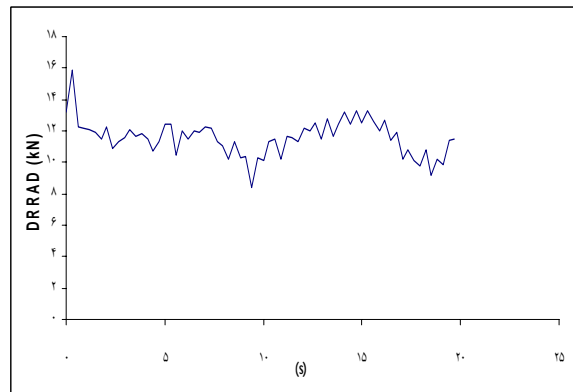
RRAD

(Draft_{TPHD})

()

Draft_{AD}

(/)

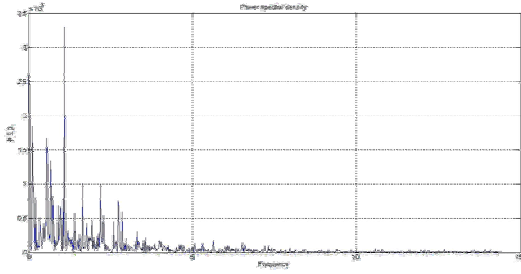


: DRRAD).

(

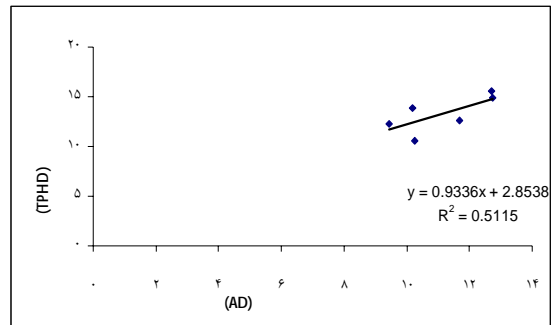
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(Alciatore & Histan, 2003)



TPHD

(GPS)



(TPHD)

(AD)

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